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# A GENERALIZED COMMON FIXED POINT THEOREM FOR TWO PAIRS OF WEAKLY COMPATIBLE SELF-MAPS

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**Abstract:** A common fixed point theorem of Rahman et al. [3] has been generalized under a weaker inequality through the notion of weak compatibility by dropping continuity and restricting the completeness of the space.

**Keywords:** Compatible and compatible maps of type A, A- and S-Compatible maps, weakly compatible self-maps and common fixed point.

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### I. INTRODUCTION

In this paper (X,d) denotes a metric space, and A, B, S and T self-maps on X.

<b>Definition 1:</b> A and S are compatible [1] if $\lim_{n \to \infty} d(ASx_n, SAx_n) = 0$	 (1)
whenever $\{x_n\}_{n=1}^{\infty}$ is a sequence in X such that	
$\lim_{n \to \infty} Ax_n = \lim_{n \to \infty} Sx_n = t$	 (2)
for some $t \in V$	

for some  $t \in X$ .

**Definition 2:** A and S are compatible of type A [3] if  $\lim_{n \to \infty} d(ASx_n, SSx_n) = 0 \text{ and } \lim_{n \to \infty} d(ASx_n, AAx_n) = 0 \qquad \dots \qquad (3)$ 

whenever  $\{x_n\}_{n=1}^{\infty} \subset X$  has the choice (2).

It is known that Definition 1 and Definition 2 are equivalent if both S and A are continuous, but are independent of each other in general. Individual conditions in (3) define the following two weaker forms of Definition 2, as given in [3].

**Definition 3(a):** A and S are A-compatible if  $\lim_{n\to\infty} d(ASx_n, SSx_n) = 0$  whenever (2) holds good for some

$$\{x_n\}_{n=1}^{\infty} \subset X$$
.

**Definition 3(b):** A and S are S-compatible if  $\lim_{n\to\infty} d(\operatorname{SAx}_n, \operatorname{AAx}_n) = 0$  whenever (2) holds good for some

 $\{x_n\}_{n=1}^{\infty} \subset X$ .

With these notions Rahman et al. [3] proved the following.

Theorem 1. Let A, B, S and T be self-maps on X satisfying the inclusion



(4)

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$$A(X) \subseteq T(X), B(X) \subseteq S(X)$$

and the inequality

 $[d(Ax,By)]^2 \leq ad(Ax,Sx)d(By,Ty) + bd(By,Sx)d(Ax,Ty) + cd(Ax,Sx)d(Ay,Ty)$ 

$$+ ed(By, Ty)d(By, Sx) + fd^{2}(Sx, Ty)$$
  
for all x, y  $\in$  X, .... (5)

for all 
$$x, y \in X$$
, ...

where a, b, c, e and f are nonnegative number such that a + b + 2c + e + f < 1. Given  $X_0 \in X$  there exist points  $x_1, x_2, \dots$  in X such that

 $Ax_{2n-2} = Tx_{2n-1} = y_{2n-1}$  and  $Bx_{2n-1} = Sx_{2n} = y_{2n}$ , n = 1, 2, 3, ...(6) ...

and the sequence  $\{y_n\}_{n=1}^{\infty}$  is a Cauchy sequence. Further suppose that X is complete,

- one of A, B, S and T is continuous, and (a)
- (b) (A,S) and (B,T) are either A- compatible or S-compatible.

Then A, B, S and T will have a unique common fixed point.

In this paper we obtain a generalization of Theorem 1 by

- relaxing the completeness of X,
- weakening the inequality (5),
- dropping the continuity condition (a), and
- weakening the notion of A and S compatibilities.

#### II. MAIN RESULT

**Definition 4 (cf. [2]):** Self-maps A and S are weakly compatible if they commute at their coincidence point.

Remark 1: It is easily seen that Definition 1 and Definitions 3(a)-3(b) imply Definition 4. That is weak compatibility is a weaker than compatibility, A and S-compatibilities.

**Theorem 2.** Let A, B, S and T be self-maps on X satisfying the inclusions (4) and the inequality  $d^{2}(Ax, By) \leq q \max d(Ax, Sx) d(By, Ty), d(By, Sx) d(Ax, Ty) + \frac{1}{2} d[(Ax, Sx) d(Ax, Ty)]$ 

$$d(By,Ty)d(By,Sx) + d^{2}(Sx,Ty) \qquad \text{for all } x, y \in X, \qquad \dots \qquad (7)$$

where  $0 \leq 9 < 1$ .

Suppose that

 $T(X) \cap S(X)$  is a complete subspace of X, and (c)

(A,S) and (B,T) are weakly compatible. (d)

Then A, B, S and T have a unique common fixed point.

**Proof.** Let  $x_0 \in X$  be arbitrary. Using (4) the sequence  $\{y_n\}_{n=1}^{\infty}$  can be inductively defined with the choice (6). Consider  $t_n = d(y_{n+1}, y_n)$  for n = 1, 2, 3, ... We assume that  $t_n > 0$  for all n.

Now taking  $x = x_{2n}$ ,  $y = x_{2n-1}$  in (7) and then usuing (6),

$$d^{2}(Ax_{2n}, Bx_{2n-1}) \leq q \max d(Ax_{2n}, Sx_{2n})d(Bx_{2n-1}, Ty_{2n-1}),$$
  
$$d(Bx_{2n-1}, Sx_{2n})d(Ax_{2n}, Tx_{2n-1}), \frac{1}{2}d[(Ax_{2n}, Sx_{2n})d(Ax_{2n}, Tx_{2n-1})],$$

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$$d(Bx_{2n-1}, Tx_{2n-1})d(Bx_{2n-1}, Sx_{2n}) + d^{2}(Sx_{2n}, Tx_{2n-1})$$

If  $t_{2n} > t_{2n-1}$  then  $t_{2n} \cdot t_{2n-1} < t_{2n}^2$  so that  $\frac{1}{2} [t_{2n}^2 + t_{2n} \cdot t_{2n-1}] < t_{2n}^2$  or  $\frac{1}{2} [t_{2n} + t_{2n-1}] < t_{2n}^2$ .

Using this in (8), we get

$$0 < t_{2n}^2 \le q \max\left\{t_{2n} \ t_{2n-1}, \frac{1}{2}t_{2n}(t_{2n-1} + t_{2n}), t_{2n}^2\right\} \le q \ t_{2n}^2 < t_{2n}^2$$
  
which is a contradiction since  $0 \le q < 1$ . Therefore  
 $t_{2n} \le t_{2n-1}$  for all  $n$ . ... (9)

Then using (9) in (8), we see that

 $t_{2n}^2 \le q t_{2n-1}^2 \text{ for all } n \ge 2.$  ... (10)

With a similar argument, we can show that

$$t_{2n-1}^{2} \le qt_{2n-2}^{2} \text{ for all } n \ge 2.$$
(11)
  
dly applying (10) and (11), it follows that

$$t_{2n} \le q t_{2n-1} \le q^2 t_{2n-2}^2 \le q^3 t_{2n-3}^2 \le \dots \le q^{2n-1} t^2 \text{ for all } n \ge 2.$$

Applying the limit as  $n \to \infty$ , (11) gives  $\lim_{n \to \infty} t_{2n} = 0$ , that is  $d(y_{2n}, y_{2n+1}) \to 0$  as  $n \to \infty$ , which implies that  $\{y_n\}_{n=1}^{\infty}$  is Cauchy sequence in  $T(X) \cap S(X)$ .

Then by (c), we see that  $\lim_{n \to \infty} y_{2n-1} = \lim_{n \to \infty} Ax_{2n-2} = \lim_{n \to \infty} Tx_{2n-1} = \lim_{n \to \infty} y_{2n} = \lim_{n \to \infty} Bx_{2n-1} = \lim_{n \to \infty} Sx_{2n} = z \qquad \dots (12)$ For some  $z \in T(X) \cap S(X)$  so that  $z \in T(X)$  and  $z \in S(X)$ .

Now  $z \in T(X)$  implies that z = Tp for some  $p \in X$ . (13)

We show that Bp = Tp = z. Taking  $x = x_{2n}, y = p$  in (7) we get



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 $d^{2}(Ax_{2n}, Bp) \leq q \max d(Ax_{2n}, Sx_{2n})d(Bp, Tp), \ d(Bp, Tp)d(Bp, Sx_{2n}) + d^{2}(Sx_{2n}, Tp)$  $d(Bp, Sx_{2n})d(Ax_{2n}, Tp) + \frac{1}{2}d[(Ax_{2n}, Sx_{2n})d(Ax_{2n}, Tp)]$ 

Applying the limit as  $n \rightarrow \infty$ , in this and using (12) and (13), we get

$$d^{2}(z, Bp) \le q \max\{0, 0, 0, d^{2}(Bp, z), 0\} = qd^{2}(Bp, z)$$
 so that  $Bp = z$ .

Thus Bp = Tp = z. This in view of weak compatibility of *B* and *T* gives Bz = Tz.

... (14)

Again 
$$z \in S(X)$$
 implies that  $z = S\ell$  for some  $\ell \in X$ . (15)

Then we show that  $A\ell = S\ell = z$ .

Substituting  $x = \ell$  and  $y = x_{2n-1}$  in (7), and using (12) and (15), we get

$$d^{2}(A\ell, Bx_{2n-1}) \leq q \max d(A\ell, S\ell) d(Bx_{2n-1}, Tx_{2n-1}), \ d(Bx_{2n-1}, S\ell) d(A\ell, Tx_{2n-1}) \}$$
  
$$\frac{1}{2} d[(A\ell, S\ell) d(A\ell, Tx_{2n-1})], \ d(Bx_{2n-1}, Tx_{2n-1}) d(Bx_{2n-1}, S\ell) + d^{2}(S\ell, Tx_{2n-1}) \}$$

Applying limit as  $n \to \infty$ ,

 $d^{2}(A\ell, z) \leq q \max\left\{0, 0, \frac{1}{2}\left[d(A\ell, z)d(A\ell, z), 0, 0\right]\right\} = q\frac{1}{2}d^{2}(A\ell, z)\right], \text{ which is a contradiction.}$ Hence  $A\ell = z$ . Thus  $A\ell = S\ell = z$ . By weak compatibility of (A, S), we get  $AS\ell = SA\ell$  or Az = Sz. ... (16)

Writing x = y = z in the inequality (7), and using (14) and (16), we get

$$d^{2}(Az, Bz) \leq q \max \left\{ d(Az, Sz) d(Bz, Tz), d(Bz, Sz) d(Az, Tz), \frac{1}{2} d[(Az, Sz) d(Az, Tz)], d(Bz, Tz) d(Bz, Sz) + d^{2}(Sz, Tz) \right\}$$
$$\leq q \max \left\{ 0, d(Bz, Az) d(Az, Bz), 0, 0, d^{2}(Az, Bz) \right\} = q d^{2} (Az, Bz) \Longrightarrow Az = Bz$$

Therefore from (14) and (16), it follows that

Az = Bz = Sz = Tz.Taking x = z,  $y = x_{2n-1}$  in (7), and using (12) and (17), we get

$$d^{2}(Az, Bx_{2n-1}) \leq q \max \{d(Az, Sz)d(Bx_{2n-1}, Tx_{2n-1}), d(Bx_{2n-1}, Sz) + d(Az, Tx_{2n-1}), \frac{1}{2}d[(Az, Sz)d(Az, Tx_{2n-1})], d(Bz_{2n-1}, Tx_{2n-1})d(Bx_{2n-1}, Sz), d^{2}(Sz, Tx_{2n-1})\}$$

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(17)



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Applying limit as  $n \to \infty$ ,

 $d^{2}(Az,z) \leq q \max\{0,d(z,Az)d(Az,z),0,0,d^{2}(Az,z)\} = qd(Az,z) \Longrightarrow Az = z.$ 

In view of (17) then it follows that z is a common fixed point of self-maps A, B, S and T.

Uniqueness of the common fixed point follows easily from the inequality (7).

**Remark 2.** The completeness of the space *X* is restricted to that of its subspace, namely  $T(X) \cap S(X)$  (cf. Condition (c) of Theorem 2). Condition (b) imples (d) in view of Remark 1. Further the inequality (5) implies (7) with the choice q = a + b + 2c + e + f. It is important to note that the continuity of none of the four maps is needed to obtain a fixed point. Thus Theorem 2 is a generalization of Theorem 1.

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